Version: V3.2.0-20230907

1, Change slam load and save map method.

Version: V3.2.0-20230516 1,Remove 2085V5 RGBD limit.

Version: V3.2.0-20230316

1,For 2085V4 and 2085V5 devices, the viewer closes the RGBD window of

Version: V3.2.0-20230228

1, Remove Slam resume/pause and Fisheye set framerate UI.

Version: V3.2.0-20230130

1,Fix SGBM setting position issue.

2,Add 2 RGB cameras function in viewer.

3,Add slam pause/resume function.

4,Add "set gamma" function in TOF IR view.

5, Modify viewer to support andorid log.

Version: V3.2.0-20221107

- 1, Add af/mf function in viewer.
- 2, Add Hid function in viewer.
- 3, Add glass log function in viewer.
- 4, Optimize UI.
- 5, Remove stereo switch resolution function.
- 6, Fix issue that slam can load and save map at the same time.

Version: V3.2.0-20221008

- 1, Fix slam issue.
- 2, Modify tofir interface to support hot plug.
- 3, Fix cslam save map issue.
- 4, Fix issue that after reset slam, locatized of load map does not change.

Version: V3.2.0-20220831 1,Fix stereo crash issue. 2, Fix android viewer issue.

3, increase getdevices time

- 4, Fix imagedata memory leak issue.
- 5, Add save path function in SlamView.
- 6, Fix issue that slam still detected planes after closing tof camera.
- 7, Fix windows crash issue.
- 8, Add CNN change source function.
- 9, Add android CNN function.
- 10, Update Stereo CNN function.
- 11, Fix issue that viewer will crash when save tof image with chinese path.
- 12, Optimize UI.

Version: V3.2.0-20220811

- 1, Fix issue that memory leak.
- 2, Reduce the number of partial drawings and improve the efficiency of edge drawing.
- 3, Fix issue that sgbm can not switch to disparity type image.
- 4, Fix issue that turn off rgb and tof can not disable rgbd button.
- 5, Fix issue that imu can not switch to VSlam only mode first time.
- 6, Optimize Slam drawing.
- 7, Fix issue that turn on all cameras, framerate will increase after several minutes.
- 8, Fix viewer set log level issue.
- 9, Add stereo calibration info in viewer.
- 10, Add IR show function.

Version: V3.2.0-20220725

- 1, Fix issue that cameras will blocked when all sensor is turned on.
- 2, Fix issue that android viewer sometimes will crash when switch slam view.
- 3, Fix caton issue when turn on all camera serveral minutes under andorid platform.
- 4, Fix sgbm memory leak problem.
- 5, Fix issue that turn off rgb and tof can not disable rgbd button.
- 6, Fix issue that imu can not switch to vslam only mode first time.
- 7, Optimize Slam drawing
- 8, Fix issue that turn on all cameras ,framerate will increase after serveral minutes.

Version: V3.2.0-20220721

- 1. Fix imu no data issue.
- 2. Fix windows crash when use sougoupinyin.
- 3. Add plane view and top view of Slam trajectory.
- 4. Fix Slam crash issue on android platform.

Version: V3.2.0-20220707

1. Fix issue that sgbm color bar can not switch to Default.

- 2. Fix Bug SDK-46 that modify UI words.
- 3. Fix issue that after clicking reset on the slam view, a yellow line will appear.
- 4. Optimize viewer startup speed.
- 5. The save path of picture will be displayed when saving the picture or pressing and holding the save button.
- 6. Fix issue that add loop closure and Load function on viewer.

Version: V3.2.0-20220629

- 1, Add CNN Model input control widget to set CNN Model file.
- 2. Add sgbm color bar function and Add depth info show when CNN enabled if sgbm is running.
- 3. CNN function can turn on or turn off.
- 4. Fix issue that SGBM average depth does not update after fillholes function is turned off.

Version: V3.2.0-20220624

- 1. Fix issue that viewer slam roll pitch yaw data display error.
- 2. Fix issue that slam can not detect plane in Host-stereo mode on android platform.
- 3. Change viewer UI.
- 4. The tof setting interface can be adjusted automatically according to different devices(Pmd tof and sony tof).
- 5. Add start video(android platform not support).
- 6. Add software icon.
- 7. Fix crash issue that when rgb and tof run at the same time.
- 8. Fix issue that sgbm avg depth does not display.
- 9. Fix issue that tof avg depth does not display.
- 10. Optimize UI
- 11. Add function that stereo, rgb, tof, sgbm can save currentsensor image through the save image button.
- 12. Add function that depth info will shown when CNN detect person or other item.
- 13. Fix issue that sometimes viewer will print unused log.
- 14. Add function that tof can switch color bar.
- 15. Add function that every sensor can switch the display mode by button.

Version: V3.2.0-20220520

- 1. Fix the problem that the xvsdk-viewer on the Android side is stuck after hot-plugging.
- 2. Modify the style of Info menu, this menu just can show informations.
- 3. Support function about TOF depth show.
- 4. Support function about TOF AVG depth show.
- 5. Support function about downsample.
- 6. Fix android viewer hotplug issue.
- 7. Change FE gain range to 1 16.
- 8. Fix issue that can not run slam when switch fe resolution to VGA second time.

- 9. Fix the issue that when the copy button is clicked on the INFO interface, the copied content is all version.
- 10. Fix issue that xvsd-viewer SLAM view does not show the picture if free-view is checked.
- 11. The FE resolution switching function is removed.
- 12. Fix issue that tof AVG depth show error when tof resolution change to QVGA.
- 13. Fix issue that viewer will crash when click slam Loop Closure button under android platform.
- 14. Fix the problem that the depth information is not displayed when the mouse is moved outside the TOF display area.
- 15. Fix the problem that the slam setting interface blocks the setting key.
- 16. Add function that when run viewer add -c option,the viewer will show log(./xvsdk_viewer -c).

Version: V3.2.0-20220510

Description:

1. Android viewer optimization

- a)Each camera of the viewer can be switched on and off independently.
- b)The viewer can display multiple camera windows and switch windows by sliding left and right.
- 2. Added viewer version number management.
- 3. The UI interface for saving videos on the Viewer is removed.
- 4. Fix the problem that the SGBM depth information of viewer 720P firmware is not displayed.
- 5. When the resolution of the stereo is 720P, turn off the slam function.
- 6. Fixed the problem that when the stereo resolution is 720P and the stereo is re-opened, there is no picture.
- 7. Fixed the problem that tof setting interface is not fully displayed on the screen under the android platform.
- 8. Fix bug that is edge mode slam not work.
- 9. Add translate function and remove eyetracking view.
- 10. Fix bug that info button not display under android paltform.
- 11. Fix issue that viewer sgbm depth show.

Version: V3.2.0-20220406

Description:

- 1. Added independent switches for slam and stereo
- 2. android viewer display scale optimization
- 3. rgbd switching stability optimization

Version:20220321

Description:

- 1. Added RGBD viewer (no 3d display yet)
- 2. Modify the default configuration parameters of sgbm:

static struct xv::sgbm_config global_config = {

1, //enable dewarp

```
1.0, //dewarp_zoom_factor
     0, //enable disparity
     1, //enable depth
     0, //enable_point_cloud
     0.08, //baseline
     96, //fov
     255, //disparity confidence threshold
     1, //enable_gamma
     2.2, //gamma_value
     0, //enable_gaussian
     0, //mode
     8000, //max_distance
     100, //min_distance
};
3. Added tof gyga resolution switch
_____
Version:20220305
Description:
1.vga tof mode 设置:
   Freq: SF|DF
   mode:IQ|M2 |edge
   FPS:5-30
   Note that due to performance impact, the fps setting item is not output in some modes
according to the actual setting mode,
   the fps in the following table shall prevail:
        IQ DF:30FPS
        IQ SF:30FPS
        M2 DF:4.5FPS
        M2 SF:13FPS
        M2 DF:3.5FPS
        M2 SF:7FPS
2. Andoroid version
3. Fisheye resolution VGA/720P switch, need to match the firmware after version 20220305
4.rgb frame rate switch, needs to match the firmware after version 20220305
_____
Version:20220220
Description:
1. Add resolution switch;
2. change the default settings of sgbm:
    1.baseline
                  0.11285 => 0.08
    2.mode
                    1
                            => 0
    3.max_distance 5000
                           => 8000
    4.fov
                   69
                           => 96
```

5.confidence 255 => 230

- 3. Add the minimum distance setting of vga tof to modify the rendering method; (color map)
- 4. Add radiobutton (hidden), release it when both firmware and sdk are ready;
- 5. Optimize sgbm real-time depth data UI interface;

Version: 20220125

Description:

- 1. Add sgbm viewer;
- 2. Add vga tof viewer;
- 3. Optimize the device control that is the actual switch control of the camera by clicking the switch;